

Codebook for “Do Voters Pay Attention to Transnational Politics? Party Positions, Transnational Families, and Voter Perceptions”

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Data Sources

- Comparative Study for Electoral Systems (CSES)
- Comparative Manifesto Project (CMP)
- Chapel Hill Expert Survey (CHES)
- German Longitudinal Election Study (GLES)

Variable Descriptions (Comparative Study for Electoral Systems)

eyear: Election year (Source: CSES)

self_rile: Self-reported individual ideological placement on left-right (Source: CSES)

n_cntry: Unique country identifier

cmp_party_code: Unique party identifier (Source: CMP)

size: Party vote share in last election (Source: CMP)

rile: Party ideological position on left-right (Source: CMP)

pfam_avg: Calculated average of the transnational party family’s positions. Average RILE score for all parties from the most recent proximal election prior to the focal country’s election, not including the focal country’s party. (Source: CMP)

misperception_cmp: Absolute value of the difference between a voter’s placement of the party on the left-right scale and the party’s actual position. (Source: CSES and CMP)

pfamdiv: Absolute value of the difference between a party’s actual position on the left-right scale and the *pfam_avg*. (Source: CMP)

pfamdiv_perc: Absolute value of the difference between a voter’s perception of the party’s position and the *pfam_avg*. (Source: CSES and CMP)

female: Respondent gender. 0=male, 1=female. (Source: CSES)

Age: Respondent age. (Source: CSES)

Educ: Respondent education. (Source: CSES)

Distance: Ideological distance between voter's *self_rile* and the party's actual position (*rile*). (Source: CSES and CMP)

Pid: Respondent is a partisan of the party. 0=not a partisan, 1=partisan (Source: CSES)

mag_shift: Absolute value of the distance between the party's position in *eyear* and the party's position in the past election. (Source: CMP)

enep2: Effective Number of Electoral Parties. (Source: CSES)

n_pfam: Unique identifier for party family. (Source: CMP)

ches_party_code: Unique identifier for party (Source: CHES)

misperception_ches: Absolute value of the difference between a voter's placement of the party on the left-right scale and the party's actual position. (Source: CHES and CMP)

pfamdiv_ches: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* using CHES positions. (Source: CHES)

distance_ches: Ideological distance between voter's *self_rile* and the party's actual position (*rile*). (Source: CHES and CMP)

mag_shift_ches: Absolute value of the distance between the party's position in *eyear* and the party's position in the past election. (Source: CHES)

n_pfam_ches: Unique identifier for party family. (Source: CHES)

pol_info: Index of number of correct responses to fact questions. (Source: CHES)

partyage: Age of the party at the time of the election. Calculated as the difference between *eyear* and the first election they contested. (Source: ParlGov)

w_rile: Weighted *rile* by size.

pfamdiv_dir: Difference between a party's actual position on the left-right scale and *pfam_avg*. Negative values suggest a left-wing divergence. Positive values suggest a right-wing divergence. (Source: CMP)

pfamdiv_change_dir: Difference between *pfamdiv* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfam_shift: Absolute value of the difference between *pfam_avg* in *eyear* and in the previous election. (Source: CMP)

left: Dummy for if the party is left-wing in the party system. 0=right parties, 1=left parties (Source: CMP)

radical: Absolute value of the difference between a party and the mean position of the party system. (Source: CMP)

radical_ches: Absolute value of the difference between a party and the mean position of the party system. (Source: CHES)

pfamdiv_change_dir_ches: Difference between *pfamdiv* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CHES)

pfam_shift_ches: Absolute value of the difference between *pfam_avg* in *eyear* and in the previous election. (Source: CHES)

pfamdiv_no_outliers: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated without outliers. (Source: CMP)

pfamdiv_yr1: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using elections one year before *eyear*. (Source: CMP)

pfamdiv_mid: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using elections held between the halfway point of the last election and *eyear*. (Source: CMP)

pfamdiv_change_no: Difference between *pfamdiv_no_outliers* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfamdiv_change_yr1: Difference between *pfamdiv_yr1* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfamdiv_change_mid: Difference between *pfamdiv_mid* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfam_shift_no: Absolute value of the difference between *pfam_avg* without outliers in *eyear* and the value for the previous election. (Source: CMP)

pfam_shift_yr1: Absolute value of the difference between *pfam_avg* calculated using only elections held within one year before *eyear* and the value for in the previous election. (Source: CMP)

pfam_shift_mid: Absolute value of the difference between *pfam_avg* calculated using only elections held within the midterm before *eyear* and the value for previous election. (Source: CMP)

Variable Descriptions (German Longitudinal Election Study)

eyear: Election year (Source: GLES)

respid: Unique identifier for respondent (Source: GLES)

pfam_div: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg*. (Source: CMP)

misperception: Absolute value of the difference between a voter's placement of the party on the left-right scale and the party's actual position. (Source: CSES and CMP)

n_pfam: Unique identifier for party family. (Source: CMP)

voter: Dummy variable for if the respondent voted for the party. 0= did not vote for the party, 1= did vote for the party. (Source: GLES)

self_rile2: Self-reported individual ideological placement on left-right (Source: GLES)

distance: Ideological distance between voter's *self_rile* and the party's actual position (*rile*). (Source: GLES and CMP)

shift: Absolute value of the distance between the party's position in *eyear* and the party's position in the past election. (Source: CMP)

pfam_shift: Absolute value of the difference between *pfam_avg* in *eyear* and in the previous election. (Source: CMP)

p_pfamdiv: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* in the previous election. (Source: CMP)

size: Party vote share in last election (Source: CMP)

misperc_lag: Absolute value of the difference between a voter's placement of the party on the left-right scale and the party's actual position in the previous election. (Source: GLES and CMP)

female: Respondent gender. 0=male, 1=female. (Source: CSES)

age: Respondent age. (Source: CSES)

govt: Dummy variable for if the party was a member of the government. 0=opposition, 1= governing party. (Source: GLES)

pfam_div_change: Difference between *pfamdiv* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

perc_div: Absolute value of the difference between a voter's perception of the party's position and the *pfam_avg*. (Source: GLES and CMP)

p_perc_div: Absolute value of the difference between a voter's perception of the party's position and the *pfam_avg* in the previous election. (Source: GLES and CMP)

perc_div_change: Difference between *perc_div* and *p_perc_div*.

pfamdiv_no_outliers: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated without outliers. (Source: CMP)

pfamdiv_yr1: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using elections one year before *eyear*. (Source: CMP)

pfamdiv_mid: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using

elections held between the halfway point of the last election and *eyear*. (Source: CMP)

prev_pfamdiv_no_outliers: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated without outliers in the previous election. (Source: CMP)

prev_pfamdiv_yr1: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using elections one year before *eyear* in the previous election. (Source: CMP)

prev_pfamdiv_mid: Absolute value of the difference between a party's actual position on the left-right scale and the *pfam_avg* where *pfam_avg* is calculated only using elections held between the halfway point of the last election and *eyear* in the previous election. (Source: CMP)

pfamdiv_change_no_outliers: Difference between *pfamdiv_no_outliers* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfamdiv_change_yr1: Difference between *pfamdiv_yr1* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfamdiv_change_mid: Difference between *pfamdiv_mid* in *eyear* and in the previous election. Negative values indicate divergence has decreased. Positive values indicate divergence as grown. (Source: CMP)

pfam_shift_no_outliers: Absolute value of the difference between *pfam_avg* without outliers in *eyear* and the value for the previous election. (Source: CMP)

pfam_shift_yr1: Absolute value of the difference between *pfam_avg* calculated using only elections held within one year before *eyear* and the value for in the previous election. (Source: CMP)

pfam_shift_mid: Absolute value of the difference between *pfam_avg* calculated using only elections held within the midterm before *eyear* and the value for previous election. (Source: CMP)